EXAMPLES

1. Basis Examples

Example 1.1. Consider the special case \mathfrak{sl}_2 of the general Lie algebra \mathfrak{sl}_n . An explicit basis is given by the three matrices:

$$e := \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \qquad \qquad h := \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad \qquad f := \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

The Lie bracket acts according to

$$[e, f] = h,$$
 $[h, e] = 2e,$ $[h, f] = -2f.$

Note that the matrix product satisfies

$$e \cdot f = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \notin \mathfrak{sl}_2.$$

Thus we see that while \mathfrak{sl}_2 is closed under the Lie bracket, it is *not* closed under matrix multiplication.

Example 1.2. Define the algebra of upper-triangular matrices by

$$\mathfrak{b}_n(\mathbb{K}) := \{ (a_{ij}) \in \mathfrak{gl}_n(\mathbb{K}) \, | \, a_{ij} = 0, \text{ for } i > j \},\$$

the algebra of strictly upper-triangular matrices by

$$\mathfrak{n}_n(\mathbb{K}) := \{ (a_{ij}) \in \mathfrak{gl}_n(\mathbb{K}) \, | \, a_{ij} = 0, \text{ for } i \ge j \},\$$

the algebra of diagonal matrices

$$\mathfrak{t}_n(\mathbb{K}) = \{ (aij) \in \mathfrak{gl}_n(\mathbb{K}) \, | \, a_{ij} = 0 \text{ for } i \neq j \}.$$

Note that all of them are Lie subalgebras of $\mathfrak{gl}_n(\mathbb{K})$.

Example 1.3. Let V be a K-vector space of dimension n and $\sigma : V \times V \to \mathbb{K}$ be a bilinear form. Define

$$\mathfrak{o}(V,\sigma) = \{ A \in \mathfrak{gl}(V) \, | \, \sigma(Av,w) = -\sigma(v,Aw), \text{ for all } v, w \in V \}.$$

It is a Lie subalgebra of $\mathfrak{gl}(V)$, called the *orthogonal Lie algebra*. If $A, B \in \mathfrak{o}(V, \sigma)$, then

$$\sigma([A, B]v, w) = \sigma(ABv, w) - \sigma(BAv, w)$$

= $-\sigma(Bv, Aw) + \sigma(Av, Bw)$
= $\sigma(v, BAw) - \sigma(v, ABw)$
= $-\sigma(v, [A, B]w),$

and therefore $[A, B] \in \mathfrak{o}(V, \sigma)$. If $V = \mathbb{K}^n$, there exists a (unique) matrix S such that $\sigma(v, w) = v^t S w$, for all $v, w \in V$.

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The condition $\sigma(Av, w) = -\sigma(v, Aw)$ can be written in the form

$$(Av)^t Sw = v^t A^t Sw = -v^t SAw$$

As it is satisfied for all $v, w \in V$, we conclude that $A^t S = -SA$. Therefore

$$\mathfrak{o}(V,\sigma) = \mathfrak{o}(n,S) = \{A \in \mathfrak{gl}_n(\mathbb{K}) \,|\, A^t S = -SA\}.$$

If σ is non-degenerate (or equivalently if S is invertible), we can write $S^{-1}A^tS = -A$. Therefore, we see that

$$-tr(A) = tr(S^{-1}ATS) = tr(SS^{-1}AT) = tr(A^t) = tr(A).$$

Hence $\operatorname{tr}(A) = 0$ and $A \in \mathfrak{sl}_n(k)$. For this reason the Lie algebra $\mathfrak{o}(V, \sigma)$ is also denoted by $\mathfrak{so}(V, \sigma)$ and is called the *special orthogonal Lie algebra*.

Example 1.4. If σ is symmetric non-degenerate and \mathbb{K} is an algebraically closed field with char(\mathbb{K}) $\neq 2$, then one can choose a basis of V such that σ is given by the identity matrix S = id. The algebra

$$\mathfrak{so}(n) = \mathfrak{so}(V, \sigma) = \{A \in \mathfrak{gl}_n(\mathbb{K}) \,|\, A^t = -A\}$$

consists of skew-symmetric matrices and is called the *(special)* orthogonal Lie algebra.

Example 1.5. Let σ be a skew-symmetric non-degenerate form for a vector space V. One can show that $\dim(V) = 2n$, for some natural number n, and that there exists a basis of V such that σ is given by the matrix

$$\begin{pmatrix} 0 & \mathrm{id} \\ -\mathrm{id} & 0 \end{pmatrix}$$

The algebra

$$\mathfrak{sp}(2n,k) = \mathfrak{so}(V,\sigma) = \{A \in \mathfrak{gl}_n(k) \,|\, A^t S = -SA\}$$

is called the symplectic Lie algebra.

Example 1.6. The set

$$\mathfrak{u}_n:=\{A\in\mathfrak{gl}_n(\mathbb{C})\,|\,A^*=-A\},\qquad\qquad \text{where }A^*:=\overline{A}^t$$

is a vector space over \mathbb{R} (but not over \mathbb{C}). It is a Lie subalgebra of $\mathfrak{gl}_n(\mathbb{C})$ (over \mathbb{R}), called the *unitary Lie algebra*. For example

$$\mathfrak{u}_1 = \{x + iy \in \mathbb{C} \mid x - iy = -(x + iy)\} = \{x + iy \in \mathbb{C} \mid x = 0\} = i\mathbb{R}.$$

Define the special unitary Lie algebra to be

$$\mathfrak{su}_n := \mathfrak{u}_n \cap \mathfrak{sl}_n(\mathbb{C}).$$

Example 1.7. Let σ be the symmetric non-degenerate form given by the matrix

$$\begin{pmatrix} \mathrm{id}_p & 0\\ 0 & -\mathrm{id}_q \end{pmatrix}.$$

The algebra

$$\mathfrak{so}(p,q) = \mathfrak{so}(V,\sigma) = \{A \in \mathfrak{gl}_n(k) \, | \, A^tS = -SA\}$$

is called the Lorentzian Lie algebra.

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1.1. The Witt Algebra. Consider the algebra of polynomials $\mathbb{C}[t]$. Its Lie algebra of derivations $\text{Der}(\mathbb{C}[t])$ is called the *Witt algebra*.

Let us try to find a concrete description of the Witt algebra. There is an obvious derivation

$$\frac{d}{dt}:\mathbb{C}[t]\to\mathbb{C}[t].$$

More generally, for any $f \in \mathbb{C}[t]$, the map

$$f\frac{\mathrm{d}}{\mathrm{d}t}:\mathbb{C}[t]\to\mathbb{C}[t],\qquad\qquad g\mapsto f\frac{\mathrm{d}g}{\mathrm{d}t}$$

is also a derivation. Conversely, given an arbitrary derivation δ , consider the polynomial $f := \delta(t) \in \mathbb{C}[t]$. Then

$$\delta(t^n) = nt^{n-1}\delta(t) = nt^{n-1}f = f\frac{\mathrm{d}}{\mathrm{d}t}(t^n).$$

Therefore $\delta = f d/dt$, and we see that $Der(\mathbb{C}[t]) = \mathbb{C}[t] d/dt$. Explicitly, the formula

$$\left[f\frac{\mathrm{d}}{\mathrm{d}t},g\frac{\mathrm{d}}{\mathrm{d}t}\right] = \left(f\frac{\mathrm{d}g}{\mathrm{d}t} - g\frac{\mathrm{d}f}{\mathrm{d}t}\right)\frac{\mathrm{d}}{\mathrm{d}t}$$

describes the Lie bracket of the Witt algebra.

1.2. Ideals and Quotients.

Example 1.8. Consider the Lie algebra $L = \mathfrak{sl}_2(\mathbb{K})$. We know that it has a basis e, h, f with multiplication

[h, e] = 2e, [h, f] = -2f, [e, f] = h.

This implies that

$$L' = [L, L] = L.$$

Let us build on this and show that the only ideals of L are zero and L. Let $I \subseteq L$ be a non-zero ideal and

$$ae + bf + ch \in I$$
, for some $a, b, c \in \mathbb{K}$.

a non-zero element. If $a \neq 0$, then we can apply ad_f twice and obtain

$$a[f, [f, e]] = 2af \in I.$$

If a = 0 and $b \neq 0$, we apply ad_h and obtain

$$-2bf \in I.$$

If a = b = 0 and $c \neq 0$, then we can apply ad_f and obtain

$$2cf \in I.$$

Finally, since $f \in I$ generates the whole of L as an ideal, we must have that L = I. In particular, we see that since \mathfrak{sl}_2 is not abelian, and the center $Z(\mathfrak{sl}_2)$ is an ideal, we must have that

$$Z(\mathfrak{sl}_2) = 0$$